A kinetic regime of hydrodynamic fluctuations and long time tails for a Bjorken expansion

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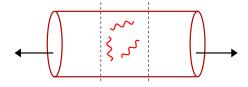
Hydrodynamics with noise

- ► Initial state fluctuations
- ▶ Thermal fluctuations for example Landau-Lifshitz

$$N_{gg}(t,k) \equiv \underbrace{\langle g^i(t,k)g^{j*}(t,k)\rangle}_{\text{momentum, } g^i \equiv T^{0i}} = \underbrace{(e+p)T\delta^{ij}}_{\text{equilibrium}}$$

- 1. Conceptually important (required by the FDT)
- 2. Larger in smaller systems: $N_{\rm particle} \sim 10000$ in the heavy-ions
- 3. Essential near a critical point

How do thermal fluctuations evolve during a Bjorken expansion? How do thermal fluctuations change the Bjorken expansion?

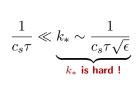


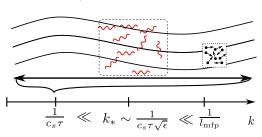
Kinetic regime of hydrodynamic fluctuations – a new scale k_{st}

- 1. For hydrodynamic fluctuations with wavenumber k:
 - ▶ Equilibration rate $\sim \gamma_{\eta} k^2$ $(\gamma_{\eta} \equiv \eta/(e+p))$ ▶ Expansion rate $\sim 1/\tau$ for a Bjorken expansion
- 2. Compete at a critical scale:

$$k_* \sim \frac{1}{\sqrt{\gamma_\eta \tau}}$$

3. Derivative expansion controlled by $\epsilon \equiv \gamma_{\eta}/\tau \ll 1$





We derive an effective description for the kinetic regime k_st

Hydro-kinetic equation: an analogy with Brownian motion



1. Langevin equation

$$\frac{dp}{dt} = \underbrace{-\gamma p}_{\rm drag} + \underbrace{\xi}_{\rm noise}, \quad \langle \xi(t)\xi(t') \rangle = 2TM\gamma\delta(t-t')$$

2. Calculate how $\langle p^2(t) \rangle$ evolves through Langevin process

$$\frac{d}{dt}\langle p^2\rangle = \underbrace{-2\gamma\left[\langle p^2\rangle - MT\right]}_{\text{equilibration}}$$

Follow the same steps for hydrodynamics with external forcing

Hydro-kinetic equation: an analogy with Brownian motion



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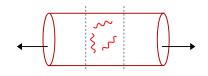
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Follow the same steps for hydrodynamics with external forcing

Hydro-Langevin equation



1. Linearized analysis in Bjorken: $e=e_0+\delta e,\ \vec{g}=(e_0+p_0)\vec{v}$ $\phi_a(t,\vec{k})\equiv(c_s\delta e,\vec{g})$

2. Hydro-Langevin equation for $\phi_a(t, \vec{k})$

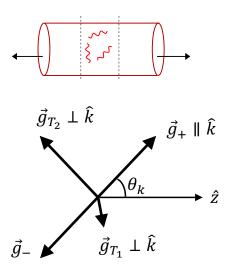
$$-\dot{\phi}(t,\vec{k}) = \underbrace{i\mathcal{L}\phi}_{\text{ideal}} + \underbrace{\mathcal{D}\phi + \xi}_{\text{viscous}} + \underbrace{\mathcal{P}(t)\phi}_{\text{expansion}}$$

3. Four eigenmodes of \mathcal{L} : ϕ_+ , ϕ_- , ϕ_{T_1} , ϕ_{T_2}

$$\underbrace{\text{left moving sound}}_{\lambda_- = -c_s k} \qquad \underbrace{\text{right moving sound}}_{\lambda_+ = c_s k} \qquad \underbrace{\text{transverse modes}}_{\lambda_T = 0}$$

The Hydro-Langevin equation in eigen basis is similar to Brownian motion

Eigenbasis in the Bjorken expansion



Hydro-kinetic equation

1. Analyze the square of the eigenmodes – for example

$$N_{++}(t,\vec{k}) \equiv \langle \phi_{+}(t,\vec{k})\phi_{+}^{*}(t,\vec{k})\rangle$$

2. Hydro-kinetic equations for N_{++} and $N_{T_2T_2}$

$$\begin{split} \dot{N}_{++} &= -\frac{4}{3} \gamma_{\eta} k^2 \left[N_{++} - T_0(e_0 + p_0) \right] - \frac{1}{\tau} \left[2 + c_s^2 + \cos^2 \theta_k \right] N_{++} \\ \dot{N}_{T_2 T_2} &= \underbrace{-2 \gamma_{\eta} k^2 \left[N_{T_2 T_2} - T_0(e_0 + p_0) \right]}_{\text{equilibration}} - \underbrace{\frac{2}{\tau} \left[1 + \sin^2 \theta_k \right] N_{T_2 T_2}}_{\text{external forcing}} \end{split}$$

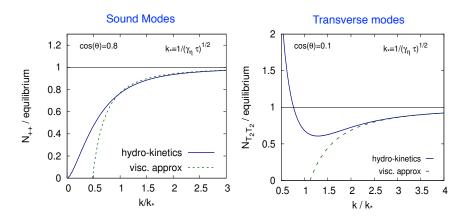
3. Neglect off-diagonal components of density matrix

$$N_{+-} \sim e^{-i(\lambda_{+} - \lambda_{-})t} \sim 0$$

No mixing between T_1 and T_2 because of rotational symmetry in xy plane

Hydro fluctuations are driven out of equilibrium at k_{st}

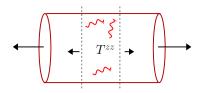
Solution of the hydro-kinetic equation Bjorken expansion at late times



 k_* is the critical scale: For larger $k \gg k_*$, closer to equilibrium

$$N_{AA} \sim N_{\sf eq} \left[1 + rac{\#}{\gamma_\eta au k^2} + \cdots
ight]$$

Evolution of the background



Hydrodynamic equation for a Bjorken expansion:

$$\frac{d}{d\tau} \left(\tau T^{\tau\tau} \right) = -T^{zz}$$

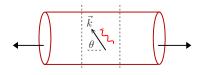
Without hydrodynamic fluctuations:

$$T^{zz} = \underbrace{p_0}_{\text{ideal}} - \underbrace{\frac{4\eta_0}{3\tau}}_{\text{1st order}} + \underbrace{(\lambda_1 - \eta \tau_\pi) \frac{8}{9\tau^2}}_{\text{2nd order}}$$

▶ Hydrodynamic fluctuations give another contributions

$$T_{\text{fluct}}^{zz} = (e_0 + p_0)\langle u^z u^z \rangle = \frac{\langle g^z g^z \rangle}{e_0 + p_0}$$

Nonlinear contributions from k_{st} to the background



1. Compute the contribution from fluctuation

$$\langle (g^z(t, \vec{x}))^2 \rangle = \int^{\Lambda} d^3k \underbrace{\left[N_{++} \cos^2 \theta_k + N_{T_2 T_2} \sin^2 \theta_k \right]}_{\sim 1 + \#/(\gamma_\eta \tau k^2) + \cdots \text{ for } k \gg k_*}$$

- lacktriangle Regularize cubic and linear UV divergences by a cutoff Λ
- 2. Renormalize the divergences c.f. Kovtun-Moore-Romatschke (11)

$$T^{zz} = \underbrace{p_0(\Lambda) + \frac{\Lambda^3 T}{6\pi^2}}_{\equiv p_{\text{phys}}} - \frac{4}{3\tau} \underbrace{\left[\eta_0(\Lambda) + \frac{17\Lambda T}{120\pi^2} \frac{e_0 + p_0}{\eta_0}\right]}_{\equiv \eta_{\text{phys}}} + \text{finite}$$

The cutoff dependence is absorbed by renormalization of p_0 and η_0

Finite contributions: Long-time tails

Evaluate the finite parts after renormalization

$$T^{zz} = \underbrace{p}_{\text{ideal}} - \underbrace{\frac{4\eta}{3\tau}}_{\text{1st order}} + \underbrace{1.08318 \ T \left(\frac{1}{4\pi\gamma_{\eta}\tau}\right)^{3/2}}_{\text{long-time tail}} + \cdots$$

Simple understanding of the scaling

$$T_{\mathrm{fluct}}^{zz} \sim \underbrace{\frac{1}{2}k_BT}_{\mathrm{equipart}} \underbrace{\int d^3k}_{\mathrm{of\ modes}} \sim Tk_*^3 \sim T\left(\frac{1}{\gamma_\eta \tau}\right)^{3/2}$$

The finite contribution from k_* gives the long-time tails

Implications for heavy-ion collisions

Plugging in typical values

$$\frac{T^3}{s} \simeq \frac{1}{13.5}, \quad \frac{\lambda_1 - \eta \tau_{\pi}}{e+p} \simeq -0.8 \left(\frac{\eta}{e+p}\right)^2$$

Compute $4\langle T^{zz}\rangle/(e+p)$

$$\begin{split} \frac{\eta}{s} &= \frac{1}{4\pi}: & 1 - 0.092 \left(\frac{4.5}{\tau T}\right) + 0.034 \left(\frac{4.5}{\tau T}\right)^{3/2} - 0.00085 \left(\frac{4.5}{\tau T}\right)^2 \\ \frac{\eta}{s} &= \frac{2}{4\pi}: & \underbrace{1}_{\text{ideal}} - \underbrace{0.185 \left(\frac{4.5}{\tau T}\right)}_{\text{1st order}} + \underbrace{0.013 \left(\frac{4.5}{\tau T}\right)^{3/2}}_{\text{1.5th order}} - \underbrace{0.0034 \left(\frac{4.5}{\tau T}\right)^2}_{\text{2nd order}} \end{split}$$

Thermal fluctuation is practically larger than 2nd order viscous correction

A few remarks on transverse pressure

There is an extra contribution from initial-time fluctuations:

$$T^{xx} = \underbrace{p}_{\text{ideal}} + \underbrace{\frac{2\eta}{3\tau}}_{\text{1st order}} - \underbrace{0.273836\ T\left(\frac{1}{4\pi\gamma_\eta\tau}\right)^{3/2}}_{\text{long-time tail}} + \underbrace{\left[\frac{\chi^{gg}_{\tau_0} + \delta\chi^{gg}_{\tau_0}}{\tau^2(e+p)^2}\right]\frac{1}{12\pi\gamma_\eta\tau}}_{\text{initial time contributions from }T}$$

initial time contributions from \mathcal{T}_1

Origin of the initial time contributions:

- ▶ Initial fluctuations with a long-range rapidity correlation $(\chi_{ au_0}^{gg})$
- lacktriangle Initial-time thermal fluctuations diffused in rapidity $(\delta\chi_{ au_0}^{gg})$

$$\Delta \eta \sim \sqrt{\frac{6\gamma_{\eta}(\tau_0)}{\tau_0}}$$

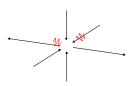
Initial and initial-time thermal fluctuations of T_1 mode contribute to T^{xx}

Comparison to previous diagrammatic calculation in static systems

c.f. Kovtun-Moore-Romatschke (11), Kovtun-Yaffe (03)

1. Apply a shear perturbation:

$$h_{xy}(t) = h_{xy}e^{-i\omega t}$$



2. Compute how N_{++} evolves away from equilibrium:

$$\dot{N}_{++} = -\gamma_{\eta} k^2 [N_{++} - N_{\rm eq}] + \dot{h}(t) N_{++}$$

3. Compute fluctuation contribution to stress in the linear order of h:

$$T^{xy} = p_0 h^{xy} + \eta_0 \dot{h}^{xy} + \frac{\langle g^x g^y \rangle}{e_0 + p_0}$$

4. Separate divergent and finite contributions in $\langle g^x g^y \rangle$:

$$\langle g^x g^y \rangle \sim \int_k \frac{i\omega}{-i\omega + \gamma_n k^2}$$

Follow the same procedure with the Bjorken expansion

Result for shear response function

Linear response of $T^{xy}(\omega)$ to $h_{xy}(\omega)$

c.f. Kovtun-Moore-Romatschke (11), Kovtun-Yaffe (03)

$$\begin{split} G_R(\omega) &\equiv \frac{T^{xy}(\omega)}{h^{xy}(\omega)} = \underbrace{\left(p_0 + \frac{\Lambda^3 T}{6\pi^2}\right)}_{\equiv p_{\rm phys}} - i \underbrace{\left(\eta_0 + \frac{17\Lambda T}{120\pi^2\gamma_\eta}\right)}_{\equiv \eta_{\rm phys}} \omega \\ &+ \underbrace{\left(1 + i\right) \frac{\left(\frac{3}{2}\right)^{3/2} + 7}{240\pi} T \left(\frac{\omega}{\gamma_\eta}\right)^{3/2}}_{\text{long-time tail}} \end{split}$$

Comments:

- Diagrams: Computation in a flat space
- ► Kinetic: Computation in a curved space

The hydro-kinetic theory reproduced the previous result with diagrams

Summary & Outlook

- ▶ Hydro-kinetic equation for k_* , advantageous in expanding systems
- ▶ Universal renormalization of pressure $p_0(\Lambda)$ and viscosity $\eta_0(\Lambda)$
- ▶ Background-dependent long-time tails $\propto \tau^{-3/2}, \omega^{3/2}$
- ► Alternative way to solve the hydrodynamics with noise

$$d_{\mu}T^{\mu\nu} = 0$$
, $\dot{N}_{AA} = \cdots$, $T^{\mu\nu} = T^{\mu\nu}_{\mathsf{bkg}} + \int_{k} N_{AA}$,

▶ Bulk viscosity renormalization for nonconformal fluid

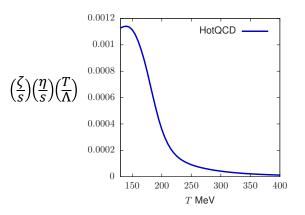
YA-Mazeliauskas-Teaney, in preparation

$$\zeta = \zeta_0(\Lambda) + \frac{\Lambda T^2}{2\pi^2} \left[\left(\frac{1}{3} + \frac{T}{2} \frac{dc_s^2}{dT} - c_s^2 \right)^2 \frac{s}{\frac{4}{3}\eta} + \left(\frac{1}{3} - c_s^2 \right)^2 \frac{2s}{\eta} \right]$$

► Application to critical dynamics YA-Teaney-Yan-Yin, in progress

Bulk viscosity from thermal fluctuations

- ▶ Use lattice EoS by Hot QCD Collaboration
- ▶ For $\zeta_0(\Lambda) = 0$ case



Bulk viscosity from thermal fluctuations enhances near T_c^{st}

Thank you for your attention!